

Taming Strategy Logic: Non Recurrent Fragments

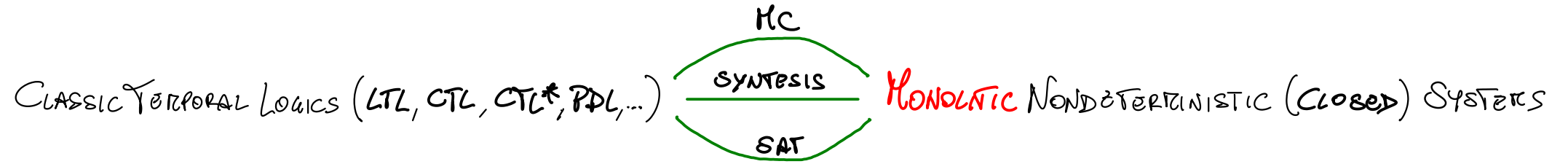
Fabio Mogavero

UNIVERSITÀ DEGLI STUDI DI NAPOLI FEDERICO II

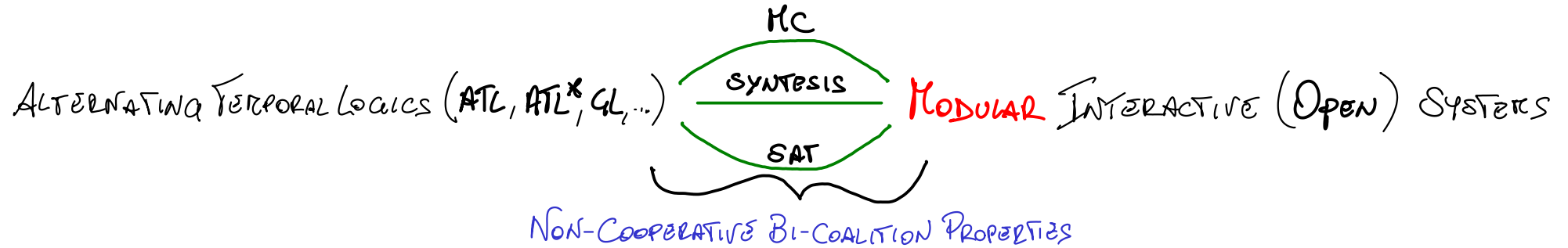
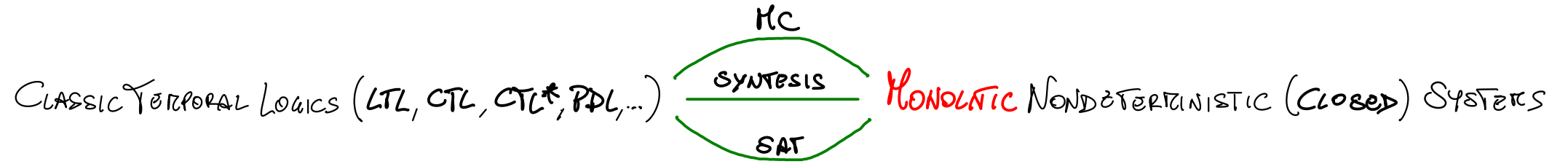
(joint work with MASSIMO BENERACETTI & ADRIANO PERON)

Time '22
November 9, 2022

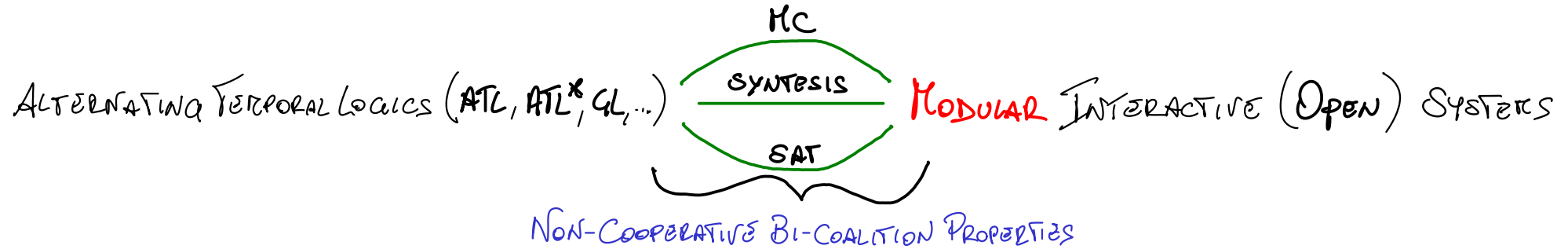
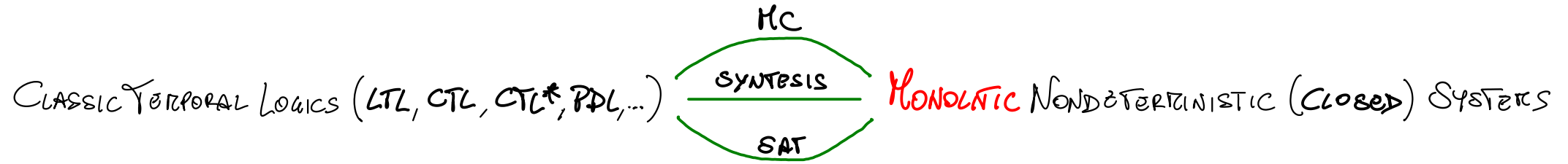
FROM TEMPORAL TO STRATEGIC REASONING



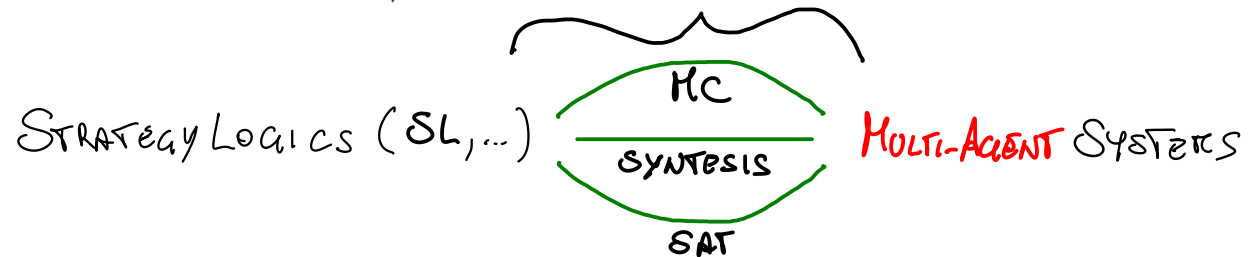
FROM TEMPORAL TO STRATEGIC REASONING



FROM TEMPORAL TO STRATEGIC REASONING



COOPERATIVE/NON-COOPERATIVE MULTI-COALITION PROPERTIES



WHAT IS KNOWN ABOUT STRATEGY LOGIC

MODEL CHECKING

EXPTIME- ϵ

SL

SL[Nq]

SL[Bq]

SL[Eq]

SL[Aq]

SL[Cq]

SL[Dq]

SL[Aq]

ATL*

CTL*

2EXPTIME- ϵ

PSPACE- ϵ

SATISFIABILITY

UNDECIDABLE

SL

SL[Nq]

SL[Bq]

SL[Eq]

SL[Aq]

SL[Cq]

SL[Dq]

SL[Aq]

ATL*

CTL*

UNKNOWN

2EXPTIME- ϵ

OUR CONTRIBUTION

WE STUDY NEW FRAGMENTS OF STRATEGY LOGIC WITH SAT EASIER THAN MC

+ HIGHLIGHT A DEEP CONNECTION BETWEEN FRAGMENTS OF FOL AND SL

+ ANALYSE NEW CLASSES OF TREE MODELS CALLED BOUNDED-FORK TREES

+ INTRODUCE TWO NEW CLASSES OF AUTOMATA ON WORDS & TREES (BOUNDED-FORK TA & PREFIX-DETERMINISTIC WA)

Non Recurrent One-Goal Strategy Logic

ONE GOAL STRATEGY LOGIC

$$* SL[\exists a]: \begin{cases} \varphi := \mathcal{P} \mid \neg\varphi \mid \varphi \wedge \varphi \mid \varphi \vee \varphi \mid \exists b.\varphi \\ \psi := \varphi \mid \neg\psi \mid \psi \wedge \psi \mid \psi \vee \psi \mid X\psi \mid \psi \cup \psi \mid \psi R\psi \end{cases}$$

ONE GOAL STRATEGY LOGIC

$$\begin{array}{l} * SL[\exists a]: \\ \left\{ \begin{array}{l} \varphi := \mathcal{P} \mid \neg\varphi \mid \varphi \wedge \varphi \mid \varphi \vee \varphi \mid \exists b.\varphi \\ \psi := \varphi \mid \neg\psi \mid \psi \wedge \psi \mid \psi \vee \psi \mid X\psi \mid \psi U \psi \mid \psi R \psi \end{array} \right. \end{array}$$

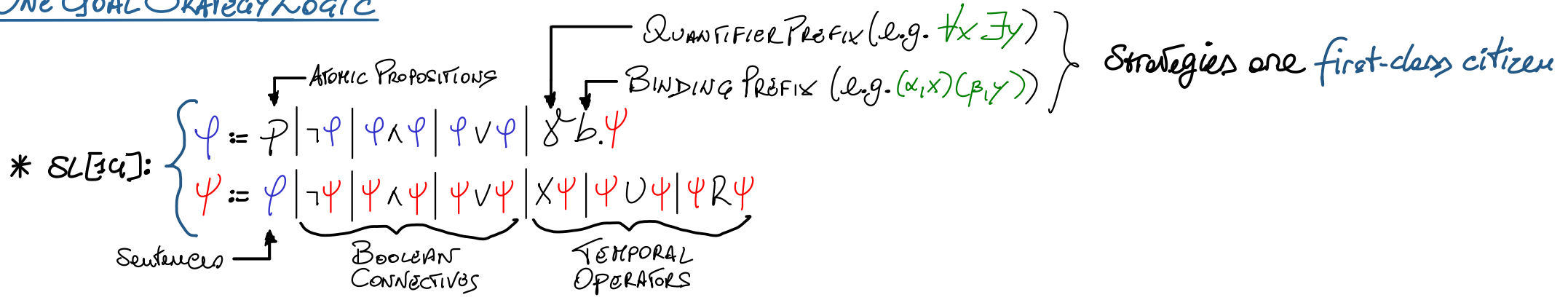
Atomic Propositions

Sentences

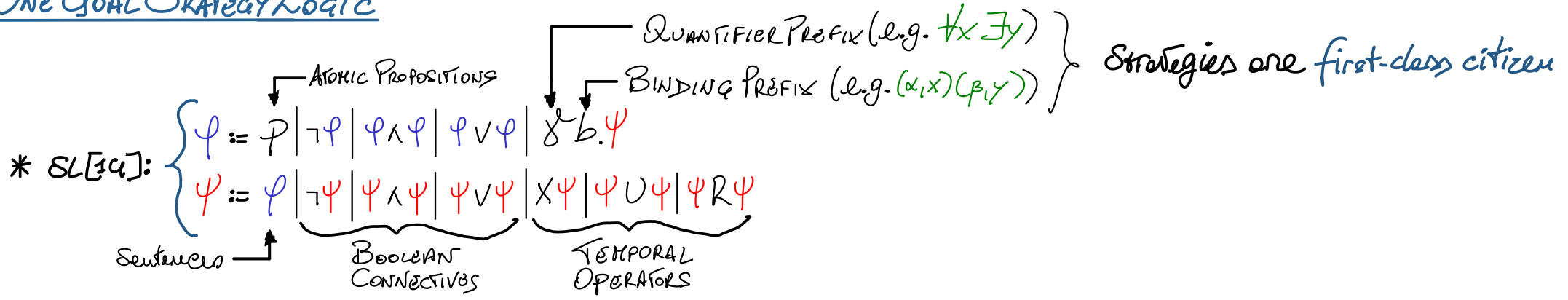
Boolean Connectives

Temporal Operators

ONE GOAL STRATEGY LOGIC

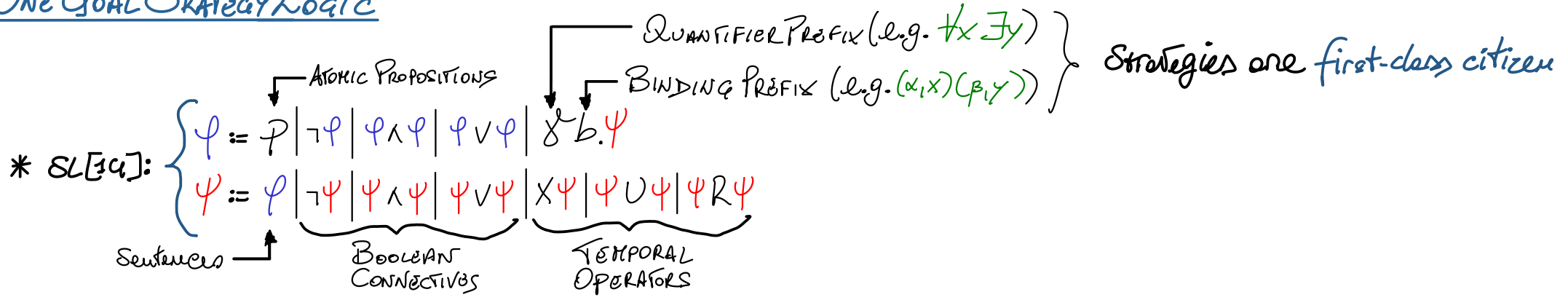


ONE GOAL STRATEGY LOGIC



* $SL[\exists a]$ generalises ATL^* to strategy quantifiers with arbitrary alternation

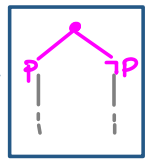
ONE GOAL STRATEGY LOGIC



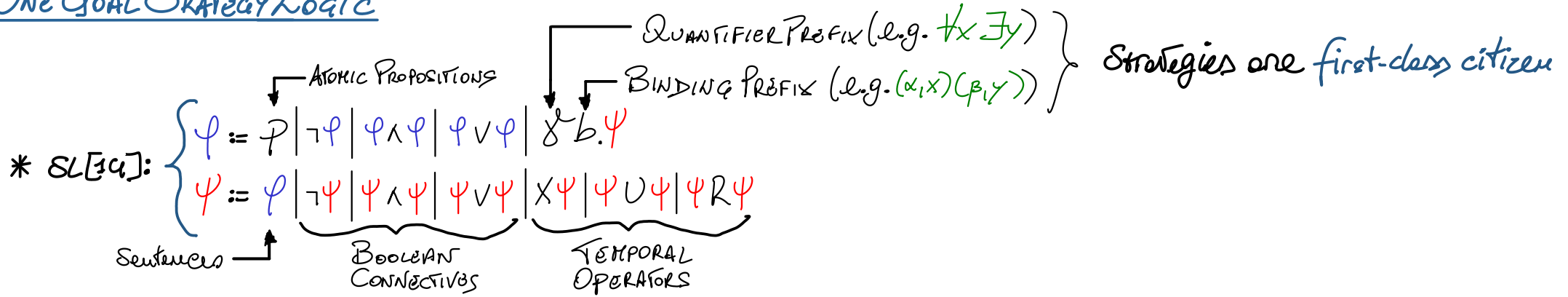
* $SL[\exists\alpha]$ generalises ATL^* to strategy quantifiers with arbitrary alternation

* Examples of simple properties:

- $\varphi \triangleq \exists x \exists y (\alpha, x)(\beta, y). \mathcal{X}_p \wedge \exists x \exists y (\alpha, x)(\beta, y). \mathcal{X}_{\neg p} \equiv \mathcal{E}\mathcal{X}_p \wedge \mathcal{E}\mathcal{X}_{\neg p}$



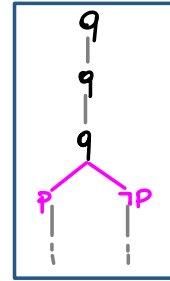
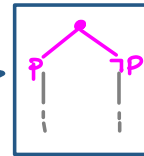
ONE GOAL STRATEGY LOGIC



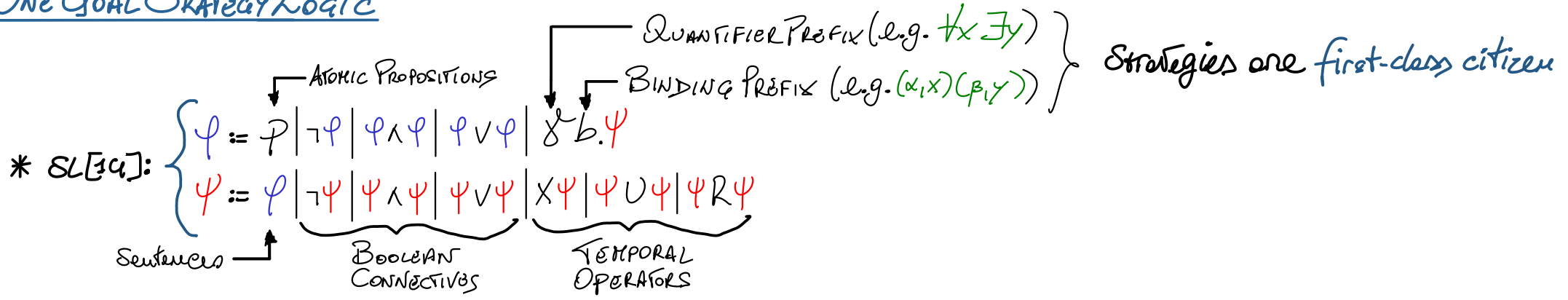
* $SL[\exists q]$ generalises ATL^* to strategy quantifiers with arbitrary alternation

* Examples of simple properties:

- $\varphi \triangleq \exists x \exists y (\alpha, x)(\beta, y). X_p \wedge \exists x \exists y (\alpha, x)(\beta, y). X_{\neg p} \equiv EX_p \wedge EX_{\neg p}$
- $\exists x \exists y (\alpha, x)(\beta, y). q U \varphi \equiv EQ U \varphi$



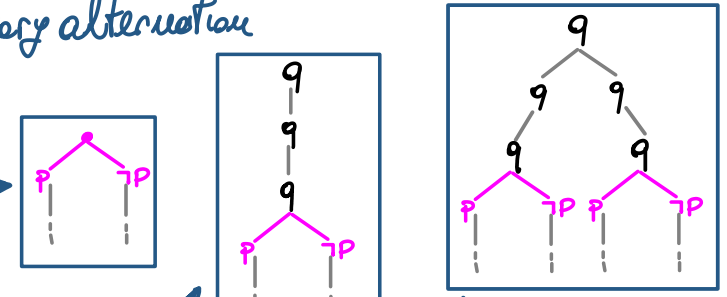
ONE GOAL STRATEGY LOGIC



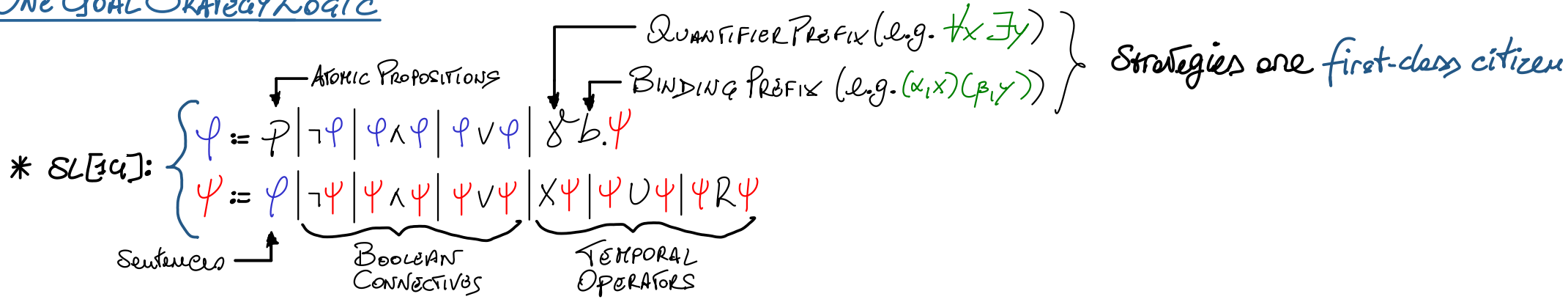
* $SL[\exists q]$ generalises ATL^* to strategy quantifiers with arbitrary alternation

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- $\exists x \exists y (\alpha, x)(\beta, y). q U \varphi \equiv EQ U \varphi$
- $\forall x \forall y (\alpha, x)(\beta, y). \varphi R q \equiv A \varphi R q$



ONE GOAL STRATEGY LOGIC

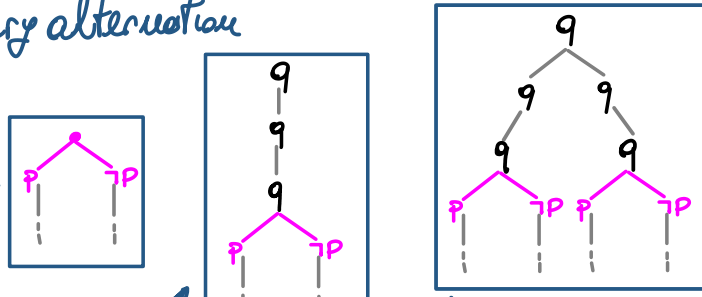


* $SL[\exists q]$ generalises ATL^* to strategy quantifiers with arbitrary alternation

* Examples of simple properties:

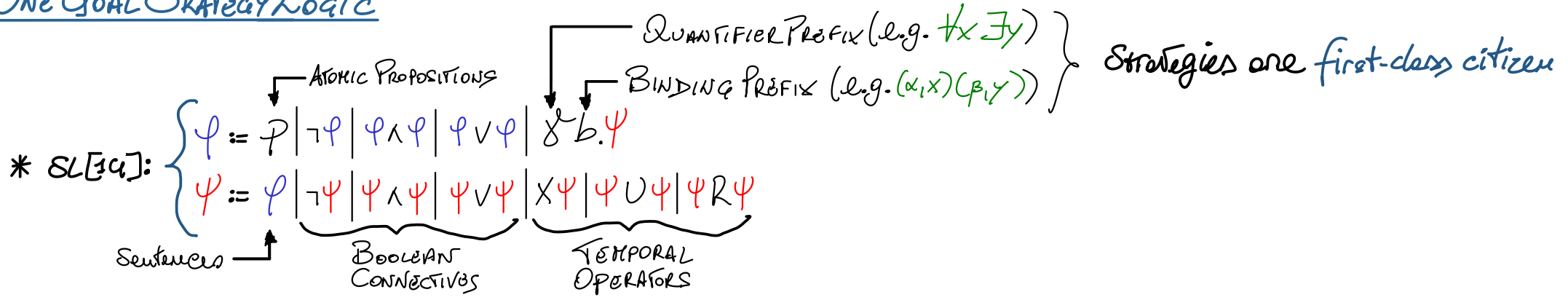
BOUNDED FOR K MODELS

- $\varphi \triangleq \exists x \exists y (\alpha, x)(\beta, y). X_p \wedge \exists x \exists y (\alpha, x)(\beta, y). X_{\neg p} \equiv EX_p \wedge EX_{\neg p}$
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- $\forall x \forall y (\alpha, x)(\beta, y). \varphi R q \equiv A \varphi R q$



← ALL PATHS HAVE A FINITE NUMBER OF BIFURCATIONS

ONE GOAL STRATEGY LOGIC

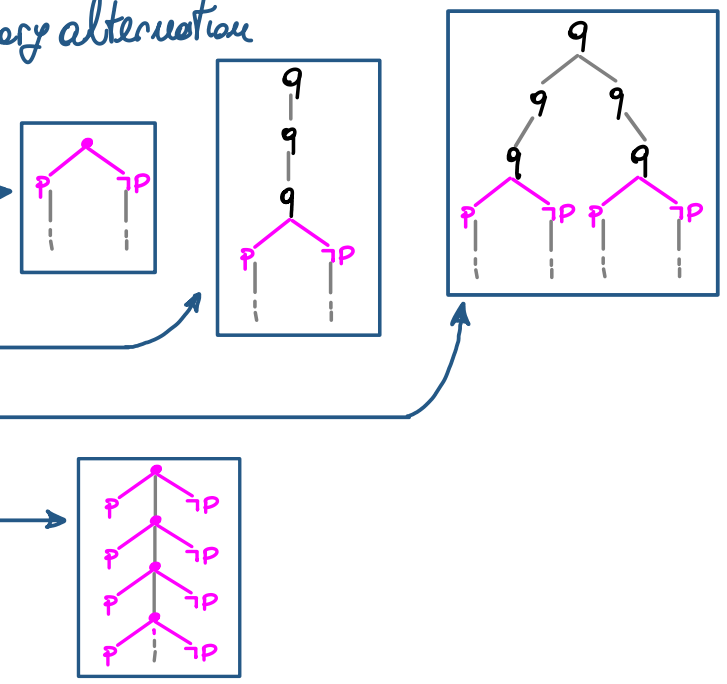


* $SL[\exists q]$ generalises ATL^* to strategy quantifiers with arbitrary alternation

* Examples of simple properties:

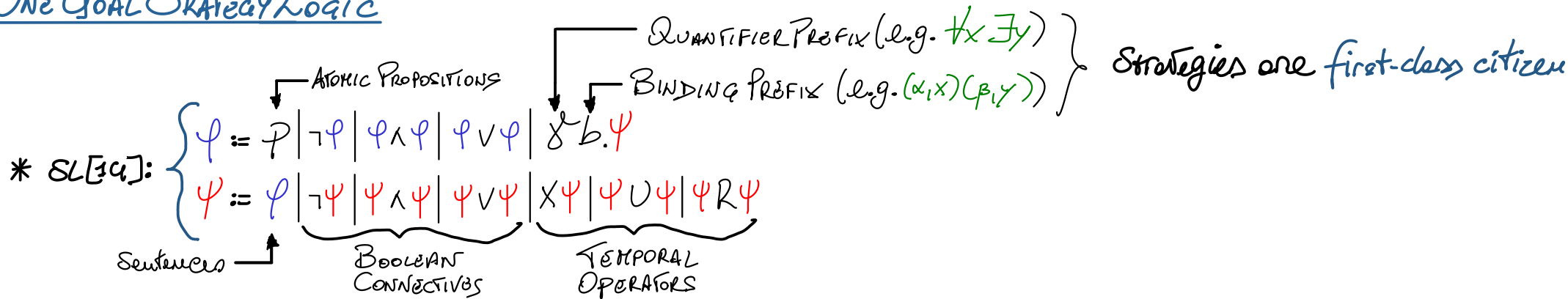
BOUNDED FOR K MODELS

- $\varphi \triangleq \exists x \exists y (\alpha, x)(\beta, y). X_p \wedge \exists x \exists y (\alpha, x)(\beta, y). X_{\neg p} \equiv EX_p \wedge EX_{\neg p}$
- $\exists x \exists y (\alpha, x)(\beta, y). q U \varphi \equiv EQ U \varphi$
- $\forall x \forall y (\alpha, x)(\beta, y). \varphi R q \equiv A \varphi R q$
- $\exists x \exists y (\alpha, x)(\beta, y). G \varphi \equiv EG \varphi$



← ALL PATHS HAVE A FINITE NUMBER OF BIFURCATIONS

ONE GOAL STRATEGY LOGIC

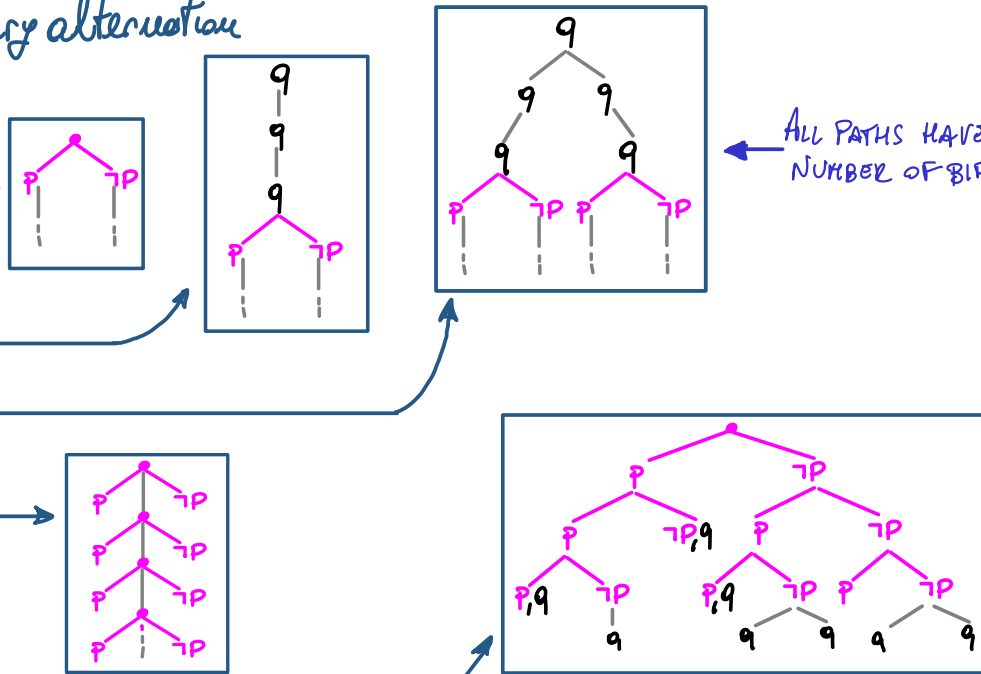


$\ast SL[\exists q]$ generalises ATL * to strategy quantifiers with arbitrary alternation

\ast Examples of simple properties:

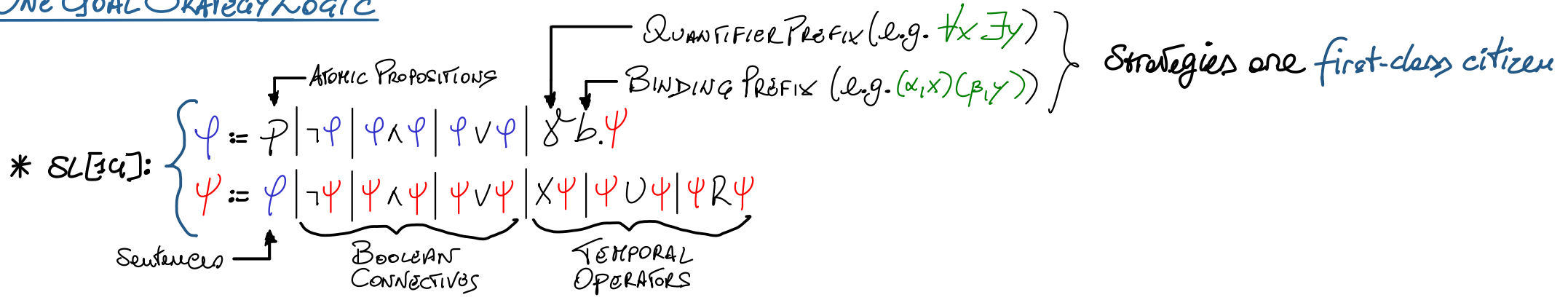
BOUNDED FOR K MODELS

- $\varphi \triangleq \exists x \exists y (\alpha, x)(\beta, y). X_p \wedge \exists x \exists y (\alpha, x)(\beta, y). X_{\neg p} \equiv EX_p \wedge EX_{\neg p}$
- $\exists x \exists y (\alpha, x)(\beta, y). q \cup \varphi \equiv EQ \cup \varphi$
- $\forall x \forall y (\alpha, x)(\beta, y). \varphi R q \equiv A \varphi R q$
- $\exists x \exists y (\alpha, x)(\beta, y). q \varphi \equiv EQ \varphi$
- $\forall x \forall y (\alpha, x)(\beta, y). \varphi \cup q \equiv A \varphi \cup q$



ALL PATHS HAVE A FINITE NUMBER OF BIFURCATIONS

ONE GOAL STRATEGY LOGIC



* $SL[\exists \forall]$ generalises ATL^* to strategy quantifiers with arbitrary alternation

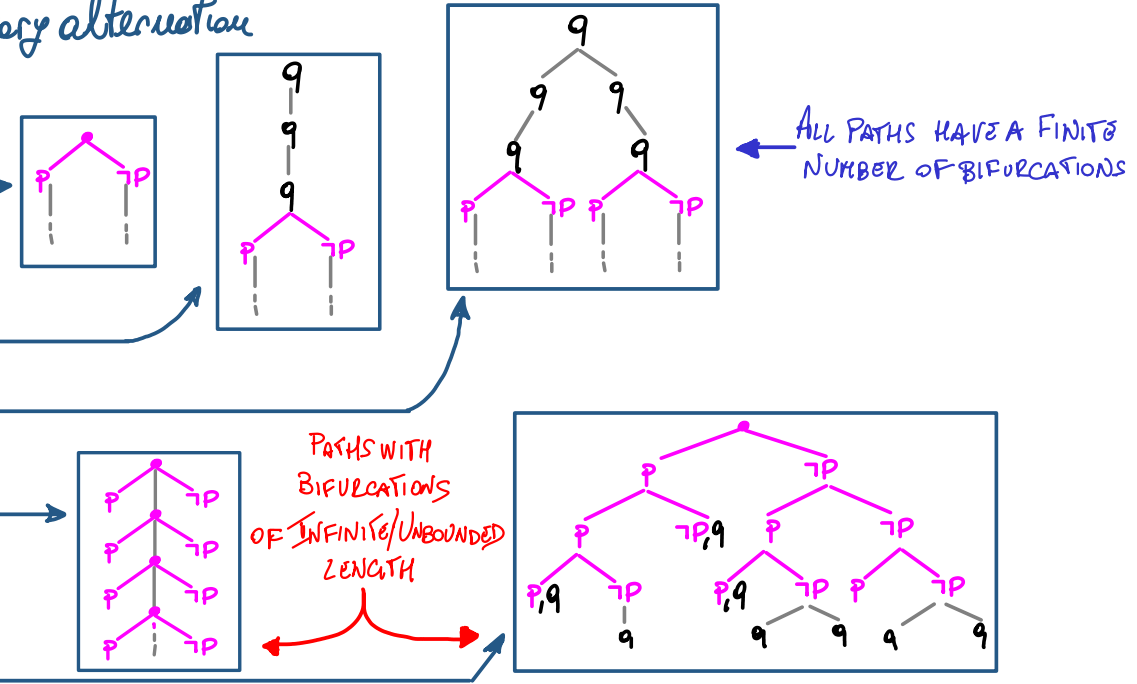
* Examples of simple properties:

BOUNDED FOR K MODELS

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- $\exists x \exists y (\alpha, x)(\beta, y). q U \varphi \equiv EQ U \varphi$
- $\forall x \forall y (\alpha, x)(\beta, y). \varphi R q \equiv A \varphi R q$

UNBOUNDED FOR K MODELS

- $\exists x \exists y (\alpha, x)(\beta, y). q \varphi \equiv EQ \varphi$
- $\forall x \forall y (\alpha, x)(\beta, y). \varphi U q \equiv A \varphi U q$



ONE GOAL STRATEGY LOGIC

$\left. \begin{array}{l} \text{QUANTIFIER PREFIX (e.g. } \forall x \exists y) \\ \text{BINDING PREFIX (e.g. } (\alpha, x)(\beta, y)) \end{array} \right\} \text{ Strategies are first-class citizen}$

$\ast SL[\exists\forall]: \begin{cases} \varphi = P \mid \neg\varphi \mid \varphi \wedge \varphi \mid \varphi \vee \varphi \mid \exists b.\varphi \\ \psi = \varphi \mid \neg\psi \mid \psi \wedge \psi \mid \psi \vee \psi \mid X\psi \mid \psi \cup \psi \mid \psi R \psi \end{cases}$

Sentences \uparrow BOOLEAN CONNECTIVES TEMPORAL OPERATORS

Satisfiability & Model Checking: Decidable in **EXPTIME-E!**

$\ast SL[\exists\forall]$ generalises **ATL*** to strategy quantifiers with **arbitrary alternation**

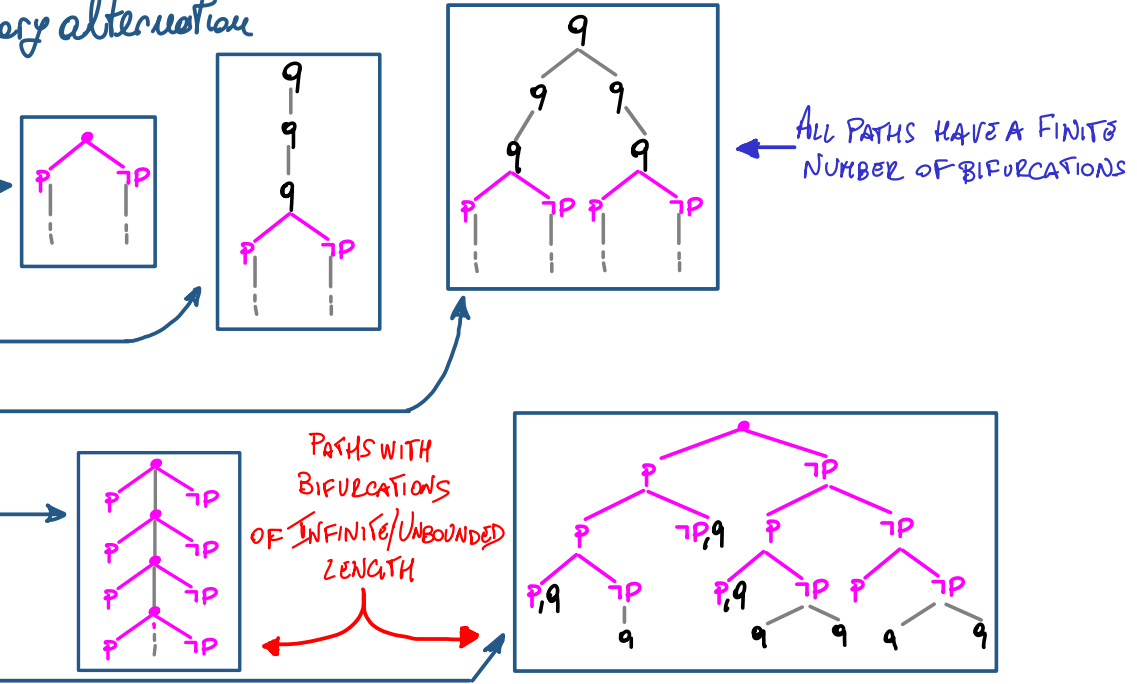
\ast Examples of simple properties:

BOUNDED FOR K MODELS

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UNBOUNDED FOR K MODELS

- $\exists x \exists y (\alpha, x)(\beta, y). q \varphi \equiv EQ \varphi$
- $\forall x \forall y (\alpha, x)(\beta, y). \varphi \cup q \equiv A \varphi \cup q$



NON-RECURRENT FRAGMENTS

$SL^{\phi}[3u]$

$\varphi := p \mid \neg\varphi \mid \varphi \wedge \varphi \mid \varphi \vee \varphi \mid \delta b.\eta \mid \delta b.\psi$

$\eta := \varphi \mid \eta \wedge \eta \mid \eta \vee \eta \mid \psi \cup \varphi \mid \varphi R \psi \mid X\eta \mid X\psi$

NON-TRIVIAL
SENTENCES ARE
FORBIDDEN

$\psi := p \mid \neg\psi \mid \psi \wedge \psi \mid \psi \vee \psi \mid \psi \cup \psi \mid \psi R \psi \mid X\psi$

Classic LTL over Atomic Propositions

NON-RECURRENT FRAGMENTS

$SL^{\phi}[3u]$

$$\varphi ::= p \mid \neg\varphi \mid \varphi \wedge \varphi \mid \varphi \vee \varphi \mid \delta b.\eta \mid \delta b.\psi$$

$$\eta ::= \varphi \mid \eta \wedge \eta \mid \eta \vee \eta \mid \psi U \varphi \mid \varphi R \psi \mid X\eta \mid X\psi$$

NON-TRIVIAL SENTENCES ARE FORBIDDEN

$$\psi ::= p \mid \neg\psi \mid \psi \wedge \psi \mid \psi \vee \psi \mid \psi U \psi \mid \psi R \psi \mid X\psi$$

Classic LTL over Atomic Propositions

$WSL^{\phi}[3u]$

$$\varphi ::= p \mid \neg\varphi \mid \varphi \wedge \varphi \mid \varphi \vee \varphi \mid \delta b.\eta$$

$$\eta ::= \varphi \mid \eta \wedge \eta \mid \eta \vee \eta \mid \beta U \varphi \mid \varphi R \beta \mid X\eta$$

NO TEMPORAL OPERATOR IS ALLOWED

$$\beta ::= p \mid \neg\beta \mid \beta \wedge \beta \mid \beta \vee \beta$$

Boolean formulae over Atomic Propositions

NON-RECURRENT FRAGMENTS

$SL^\phi[\exists a]$

$\varphi ::= p \mid \neg p \mid \varphi \wedge \psi \mid \varphi \vee \psi \mid \delta b. \eta \mid \delta b. \psi$

$\eta ::= \varphi \mid \eta \wedge \eta \mid \eta \vee \eta \mid \psi U \varphi \mid \varphi R \psi \mid X \eta \mid X \psi$

NON-TRIVIAL SENTENCES ARE FORBIDDEN

$\Psi ::= p \mid \neg p \mid \Psi \wedge \Psi \mid \Psi \vee \Psi \mid \Psi U \Psi \mid \Psi R \Psi \mid X \Psi$

Classic LTL over Atomic Propositions

$WSL^\phi[\exists a]$

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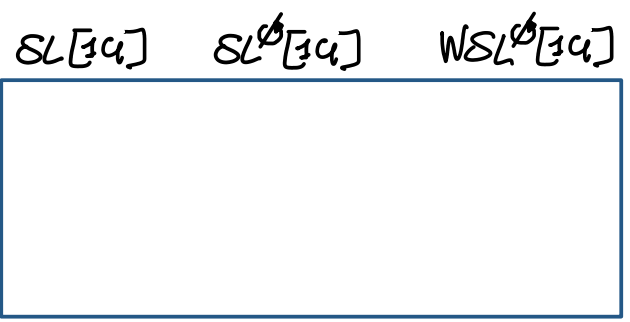
$\eta ::= \varphi \mid \eta \wedge \eta \mid \eta \vee \eta \mid \beta U \varphi \mid \varphi R \beta \mid X \eta$

NO TEMPORAL OPERATOR IS ALLOWED

$\beta ::= p \mid \neg p \mid \beta \wedge \beta \mid \beta \vee \beta$

Boolean formulae over Atomic Propositions

$\exists q \varphi, A \varphi U q$
 $A[(q R p) U \varphi], E[\varphi R (p U q)]$
 $E[(q \vee t) U \varphi], A[\varphi R (\exists s t)]$



$\varphi \triangleq EX p \wedge EX \neg p$

NON-RECURRENT FRAGMENTS

$SL^{\neq}[a]$

$\varphi ::= p \mid \neg\varphi \mid \varphi \wedge \varphi \mid \varphi \vee \varphi \mid \delta b.\eta \mid \delta b.\psi$

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Classic LTL over Atomic Propositions

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$\beta ::= p \mid \neg\beta \mid \beta \wedge \beta \mid \beta \vee \beta$

Boolean formulae over Atomic Propositions

| | $SL[a]$ | $SL^{\neq}[a]$ | $WSL^{\neq}[a]$ |
|--|---------|----------------|-----------------|
| $\exists q\varphi, A\varphi U q$ | ✓ | ✗ | ✗ |
| $A[(qR p) U \varphi], E[\varphi R (p U q)]$ | | | |
| $E[(q\vee t) U \varphi], A[\varphi R (\exists t)]$ | | | |

$\varphi \triangleq EX p \wedge EX \neg p$

NON-RECURRENT FRAGMENTS

$SL^{\neq}[a]$

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Classic LTL over Atomic Propositions

$WSL^{\neq}[a]$

$\varphi ::= p \mid \neg\varphi \mid \varphi \wedge \varphi \mid \varphi \vee \varphi \mid \delta b.\eta$
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NO TEMPORAL OPERATOR IS ALLOWED

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Boolean formulae over Atomic Propositions

| | $SL[a]$ | $SL^{\neq}[a]$ | $WSL^{\neq}[a]$ |
|--|---------|----------------|-----------------|
| $\exists q\varphi, A\varphi U q$ | ✓ | ✗ | ✗ |
| $A[(qRr)U\varphi], E[\varphi R(pUq)]$ | ✓ | ✓ | ✗ |
| $E[(qv\tau)U\varphi], A[\varphi R(\exists\alpha\tau)]$ | | | |

$\varphi \triangleq \exists X p \wedge \exists X \neg p$

NON-RECURRENT FRAGMENTS

$SL^{\neq}[a]$

$\varphi ::= p \mid \neg p \mid \varphi \wedge \psi \mid \varphi \vee \psi \mid \delta b.\eta \mid \delta b.\psi$

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NON-TRIVIAL SENTENCES ARE FORBIDDEN

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Classic LTL over Atomic Propositions

$WSL^{\neq}[a]$

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Boolean formulae over Atomic Propositions

| | $SL[a]$ | $SL^{\neq}[a]$ | $WSL^{\neq}[a]$ |
|---|---------|----------------|-----------------|
| $\exists q \varphi, A \varphi U q$ | ✓ | ✗ | ✗ |
| $A[(q R p) U \varphi], E[\varphi R (p U q)]$ | ✓ | ✓ | ✗ |
| $E[(q \vee t) U \varphi], A[\varphi R (\exists s t)]$ | ✓ | ✓ | ✓ |

$\varphi \triangleq \exists X p \wedge \exists X \neg p$

NON-RECURRENT FRAGMENTS

$SL^{\neq}[a]$

$\varphi ::= p \mid \neg p \mid \varphi \wedge \psi \mid \varphi \vee \psi \mid \delta b.\eta \mid \delta b.\psi$

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Classic LTL over Atomic Propositions

$WSL^{\neq}[a]$

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$\beta ::= p \mid \neg \beta \mid \beta \wedge \beta \mid \beta \vee \beta$

Boolean formulae over Atomic Propositions

| | $SL[a]$ | $SL^{\neq}[a]$ | $WSL^{\neq}[a]$ |
|---|---------|----------------|-----------------|
| $Ea\varphi, A\varphi U q$ | ✓ | ✗ | ✗ |
| $A[(qRr)U\varphi], E[\varphi R(pUq)]$ | ✓ | ✓ | ✗ |
| $E[(qv\tau)U\varphi], A[\varphi R(\delta a\tau)]$ | ✓ | ✓ | ✓ |

$\varphi \triangleq EXp \wedge EX\tau p$

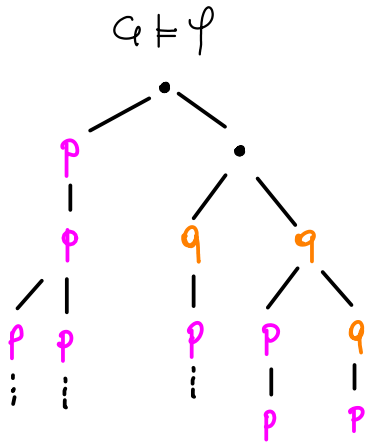
* $SL^{\neq}[a]/WSL^{\neq}[a]$ are still powerful enough to specify finite horizon (state) properties (e.g. common in communication protocols)

MODEL THEORETIC ANALYSIS

SINGLE-TIME SATISFACTION

$$\varphi = \exists x_1 p \wedge \exists x_2 p \wedge AF \left[\underbrace{A(q \cup \exists q p)}_{\varphi_2} \right]$$

φ_1

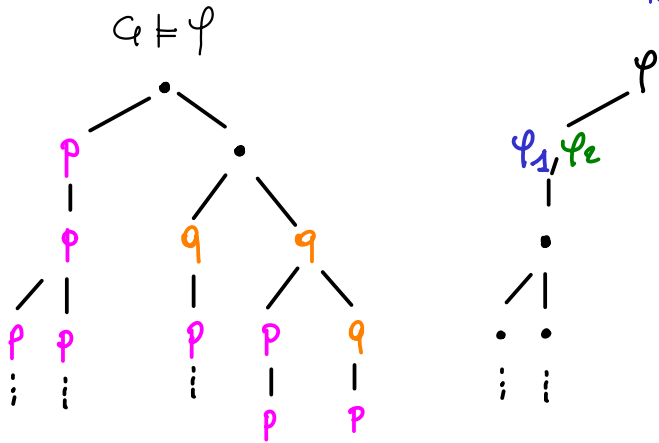


MODEL THEORETIC ANALYSIS

SINGLE-TYPE SATISFACTION

$$\varphi = \exists x_1 p \wedge \exists x_2 p \wedge \text{AF} \left[\underbrace{A(q \cup \exists q p)}_{\varphi_2} \right]$$

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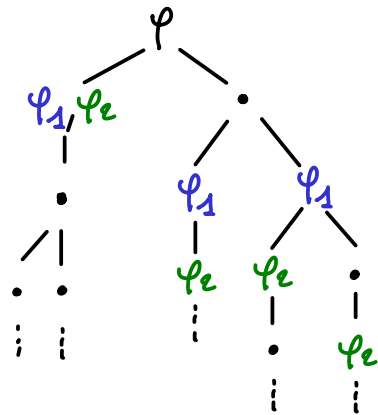
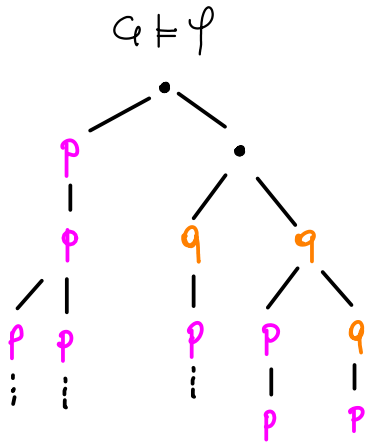


MODEL THEORETIC ANALYSIS

SINGLE-TYPE SATISFACTION

$$\varphi = \exists x_1 p \wedge \exists x_2 p \wedge \text{AF} \left[\underbrace{A(q \cup \exists q p)}_{\varphi_2} \right]$$

φ_1

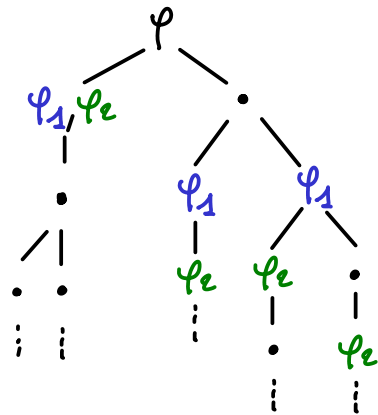
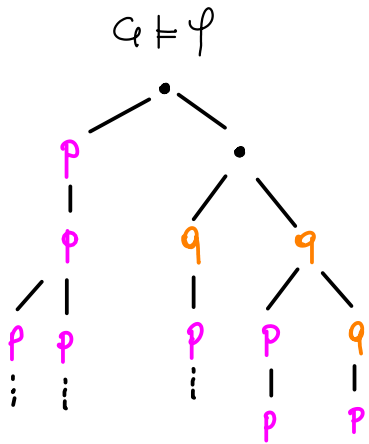


MODEL THEORETIC ANALYSIS

SINGLE-TYPE SATISFACTION

$$\varphi = \exists x_1 p \wedge \exists x_2 \neg p \wedge \text{AF} \left[\underbrace{A(q \cup \exists q p)}_{\varphi_2} \right]$$

φ_1



NORMAL MODELS

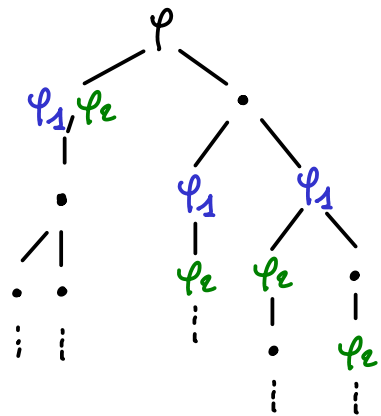
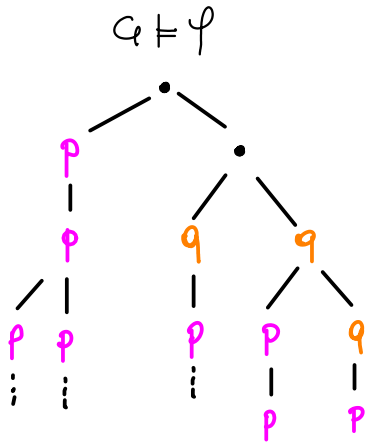
$$\varphi = [\forall x \exists y (\alpha_1 x)(\beta_1 y) \psi_1] \wedge [\exists x \forall y (\alpha_2 x)(\beta_2 y) \psi_2] \wedge [\exists x \forall z (\alpha_3 z)(\beta_3 x) \psi_3]$$

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Skolemisation
↓

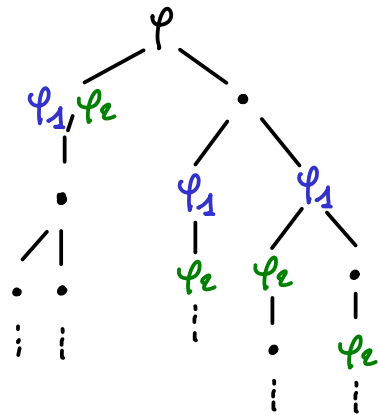
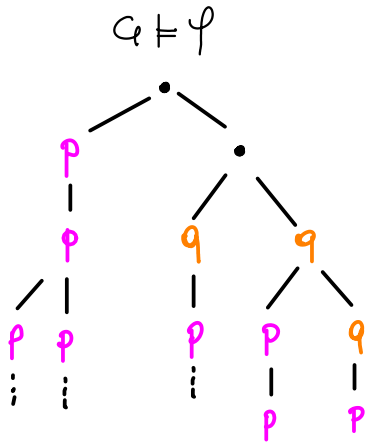
$$S_k(\varphi) = [\forall x (\alpha_1 x)(\beta_1 f(x)) \psi_1] \wedge [\forall y (\alpha_2 c_2)(\beta_2 y) \psi_2] \wedge [\forall z (\alpha_3 z)(\beta_3 c_3) \psi_3]$$

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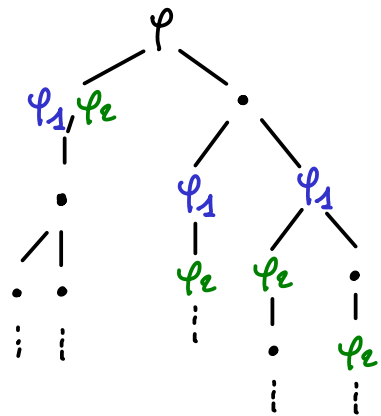
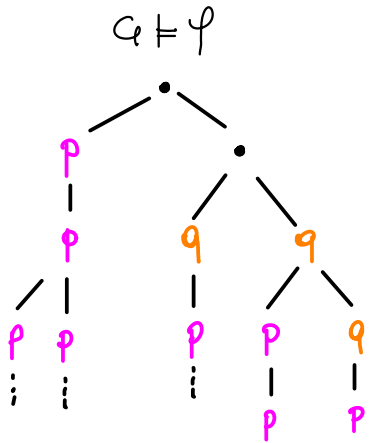
unify
 $(\alpha_1 c_1)(\beta_1 f(c_1))$

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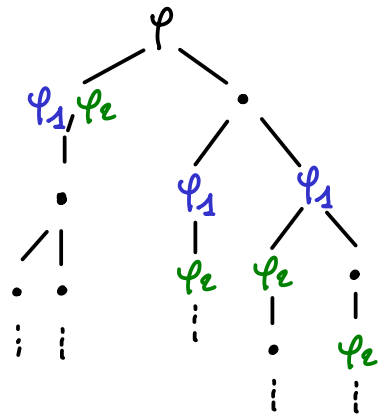
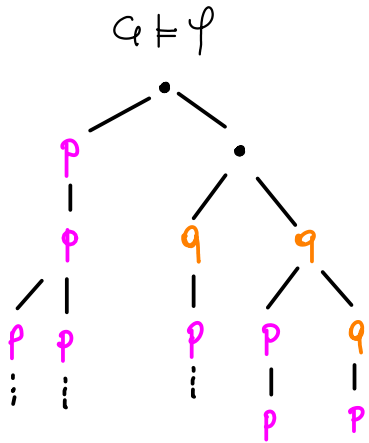
$\underbrace{\hspace{10em}}_{\text{unify } (\alpha_1 c_1)(\beta_1 f(c_1))} \quad \underbrace{\hspace{10em}}_{\text{unify } (\alpha_2 c_2)(\beta_2 c_2)}$

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Skolemisation



do not unify

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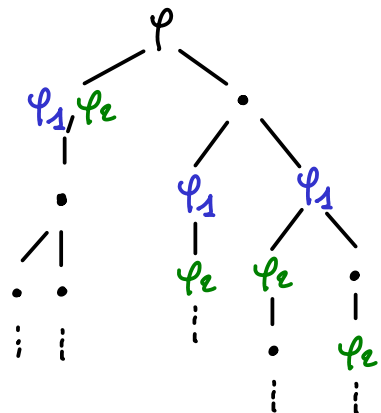
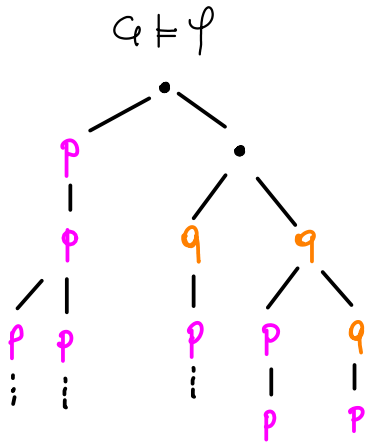
unify $(\alpha_1 c_2)(\beta_1 f(c_2))$ unify $(\alpha_2 c_2)(\beta_2 c_2)$

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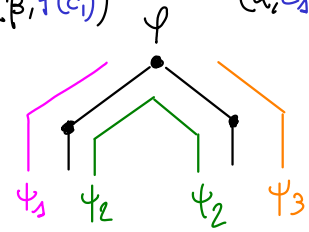
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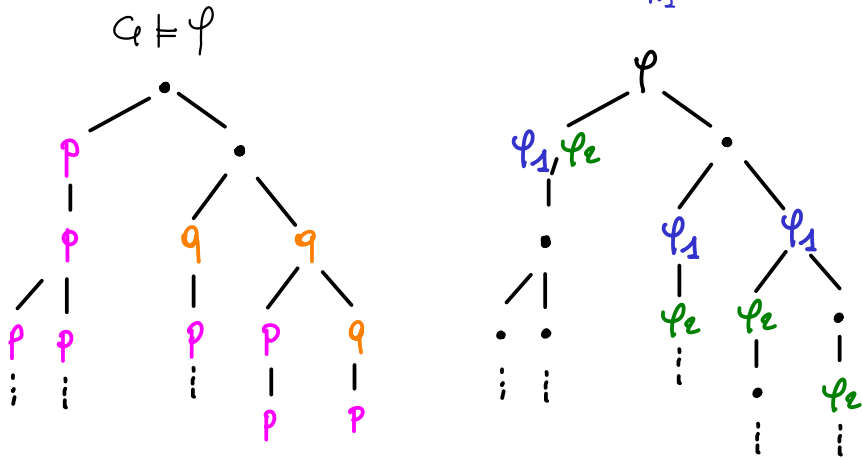


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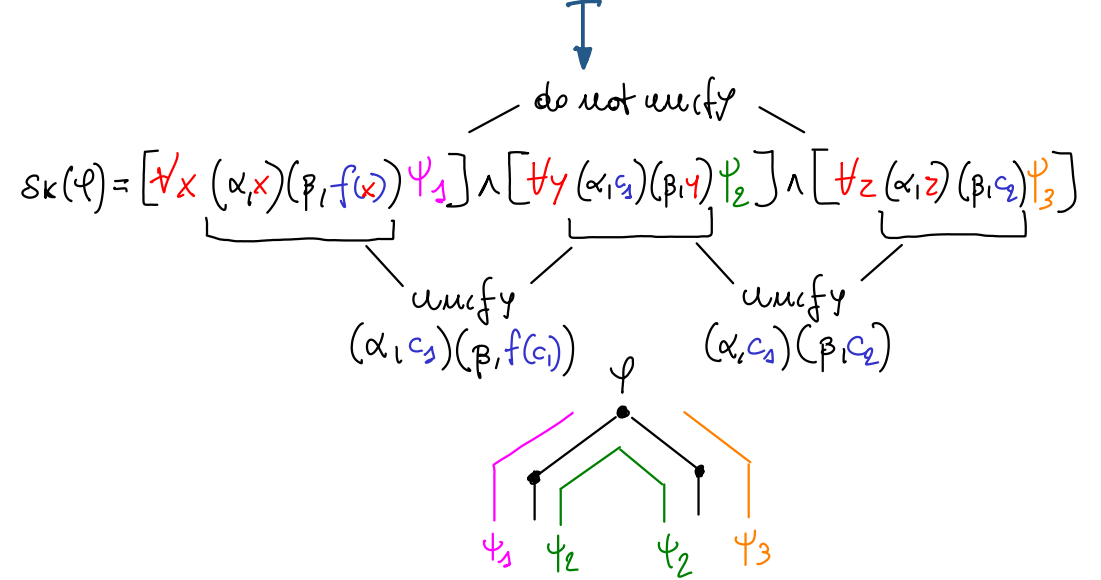
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Skolemisation



* Every $SL^{\forall}[\exists \forall]$ / $WSL^{\forall}[\exists \forall]$ satisfiable sentence has a k -fork normal model (every branch has at most k forks), with $k \leq |\varphi|$

New Classes of Automata

BOUNDED-FORK TREE AUTOMATA

* A Nondeterministic Tree Automaton is K -fork, for some $K \in \mathbb{N}$, if

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the set of states Q can be partitioned in $K+1$ sets

$$Q_K \quad Q_{K-1} \quad \dots \quad Q_1 \quad Q_0$$

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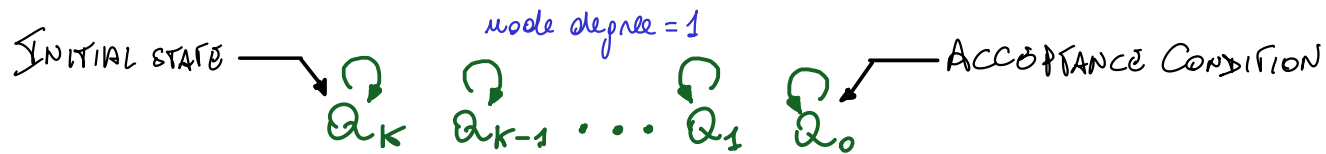
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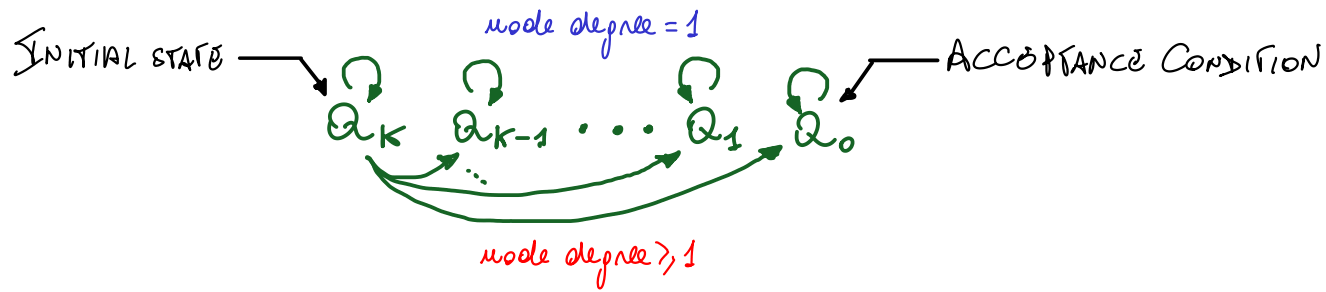
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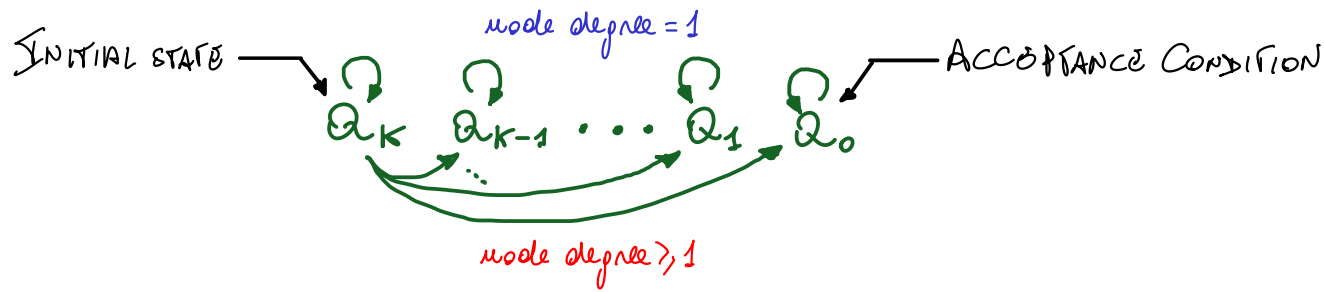
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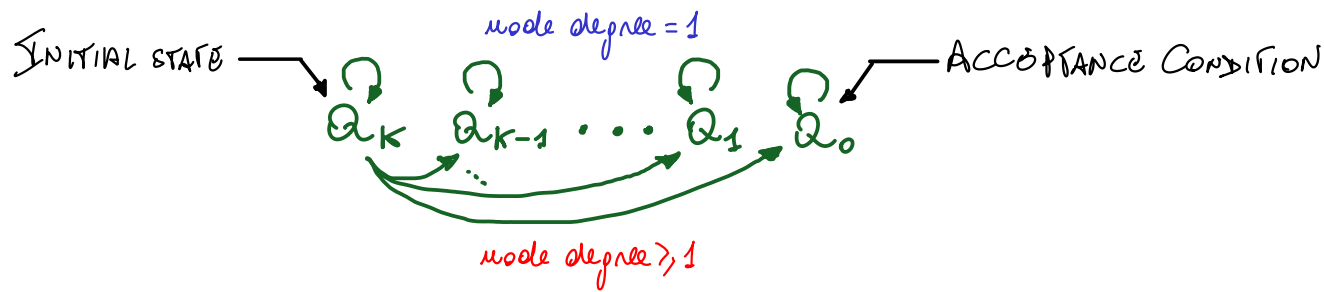
↑ For Büchi BOUNDED-FORK NTA

$\left\{ \begin{array}{l} K: \text{bound on the number of forks} \\ m: \text{number of states} \\ m: \text{number of transitions} \end{array} \right.$

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* Recall that the emptiness of Büchi NTA is PTime-E in the size of the automaton (Vardi, Wolper '86)

PREFIX-DETERMINISTIC WORD AUTOMATA

* Safeless approach to satisfiability: Find a **SUITABLE** Nondeterministic Word Automaton to run over a tree

+ A NWA \mathcal{W} is a **Good-for-Game Automaton** if $\text{wot}(\mathcal{W})$ accepts all trees \mathcal{T} whose branches are accepted by \mathcal{W}

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* Every PD-NWA is a **Good-for-Game Automaton** w.r.t. the class of bounded-fork trees

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* For every LTL/WLTL formula ψ there exists a Büchi PD-NWA \mathcal{W}_ψ with $2^{O(2^{|\psi|})} / 2^{O(|\psi|^3)}$ many states
↑ Fragment of LTL underlying $\text{WSL}^\omega[\exists a]$ ↑ $W \in \mathcal{L}(\mathcal{W}_\psi) \iff W \models \psi$

The Satisfiability Problem

AUTOMATA THEORETIC APPROACH TO SAT

* For every $SL^{\exists}[C_1]$ / $WSL^{\exists}[C_1]$ sentence φ we build a bounded-fork NFA $N_{\varphi} = \mathcal{D}_{NF} \times N_{TF}$ s.t.

AUTOMATA THEORETIC APPROACH TO SAT

* For every $SL^{\exists}[Q]/WSL^{\exists}[Q]$ sentence φ we build a bounded-fork NFA $N_{\varphi} = \mathcal{D}_{\text{NM}} \times N_{\text{TF}}$ st.

+ \mathcal{D}_{NM} : Safety Deterministic Tree Automaton verifying that the accepted tree \mathcal{T} is a K -fork normal model

↑ Exponential in the number of binding prefixes in φ

↑ number of subsentences in φ

Conclusions

Some Results

* Some Non-Recursive fragments of $SL[1a]$ have simpler satisfiability problems than model-checking problems

| | SAT | | MC |
|-----------------------|--------------------|---|--------------------|
| $SL[1a]$ | $\Delta EXPTIME-C$ | = | $\Delta EXPTIME-C$ |
| └ $SL^\emptyset[1a]$ | $AEXPTIME[k-dt]$ | ≤ | $\Delta EXPTIME-C$ |
| └ $WSL^\emptyset[1a]$ | $PSPACE-C$ | < | $\Delta EXPTIME-C$ |

SOME RESULTS

* Some Non-Recursive fragments of $SL[ca]$ have simpler satisfiability problems than model-checking problems

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| ATL^* | $\Delta EXPTIME-c$ | = | $\Delta EXPTIME-c$ |
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* Some Non-Recurrent fragments of $SL[ca]$ have simpler satisfiability problems than model-checking problems

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| $SL[ca]$ | $\mathcal{L}EXP_{TIME-0}$ | = | $\mathcal{L}EXP_{TIME-0}$ |
| └ $SL^{\phi}[ca]$ | $AEXP_{TIME}[k-dt]$ | ≤ | $\mathcal{L}EXP_{TIME-0}$ |
| └└ $WSL^{\phi}[ca]$ | $PSPACE-0$ | < | $\mathcal{L}EXP_{TIME-0}$ |
| ATL^* | $\mathcal{L}EXP_{TIME-0}$ | = | $\mathcal{L}EXP_{TIME-0}$ |
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| <hr/> | | | |
| CTL^* | $\mathcal{L}EXP_{TIME-0}$ | > | $PSPACE-0$ |
| └ $CTL^{*\phi}$ | $AEXP_{TIME}[k-dt]$ | > | $PSPACE-0$ |
| └└ $WCTL^{*\phi}$ | $PSPACE-0$ | = | $PSPACE-0$ |

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| <hr/> | | | |
| $SL[ca]$ | ? | | $\Delta EXPTIME-c$ |
| └ $FSL[ca]$ | $PSPACE-c$ | $<$ | $\Delta EXPTIME-c$ |

SOME RESULTS

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Few OPEN PROBLEMS

- * Is the satisfiability of $SL^\phi[ca]/ATL^{*\phi}/CTL^{*\phi}$ $AEXP_{TIME}[k-dt]-\mathcal{C}$?

- * What is the most expressive $PSPACE$ fragment of $SL^\phi[ca]$?

- * Are $SL[ca]/SL^\phi[ca]$ decidable?

- * What are the most expressive fragments of SL with a satisfiability problem **SIMPLER THAN** the model-checking one?

